

**Opportunity Title:** Robotic Locomotion and Whole Body Manipulation

**Opportunity Reference Code:** ARL-R-VTD-2047782940

**Organization** DEVCOM Army Research Laboratory

**Reference Code** ARL-R-VTD-2047782940

**Description About the Research**

ARL is pursuing research to increase the dynamic mobility in autonomous robotics platforms to enable agile traversal of complex environments. Physics-based multi-bodied models are used to construct simulations which aid the development of control authorities and fundamental understanding of the dynamics that govern the robotic system. These controls are transitioned to physical platforms where verification and refined tuning are demonstrated. Iterations between the model and physical platform are continued to further expand and improve performance and efficiency. These techniques are used across multiple platforms such as legged robotics and other high degree of freedom limbed systems. The candidate should be aware of techniques for validation and verification of simulations through experiments.

*ARL Advisor:* Jason Pusey

*ARL Advisor Email:* [Jason.L.Pusey.civ@mail.mil](mailto:Jason.L.Pusey.civ@mail.mil)

**About VTD**

The CCDCArmy Research Laboratory's Vehicle Technology Directorate (VTD) is the principal Army organization responsible for the pursuit of mobility-related science and technologies leading to advanced capabilities and improved reliability for Army air and ground vehicles. VTD leads the ARL Major Laboratory Program in mobility and the RDECOM Technology Focus Team in mobility and logistics. The technology focus areas within the ARL and RDECOM programs have been defined as platform, propulsion, intelligent systems and logistics.

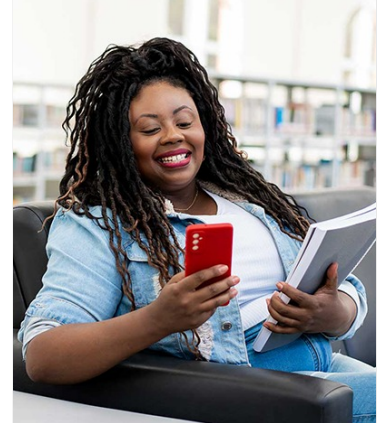
The VTD mission is accomplished through in-house basic and applied research, and from collaborations with other ARL functions, RDECOM, Navy, Air Force, academia and industry leaders. The mission is enhanced through teaming with and leveraging of research efforts associated with Collaborative Technology Alliances (CTAs) and Multidisciplinary University Research Initiatives (MURIs). For example, VTD is actively involved with two CTAs (Robotics and Micro Autonomous System Technologies), several cooperative agreements, and a unique partnership with the National Aeronautics and Space Administration (NASA) at the Langley Research Center in Hampton, VA and the Glenn Research Center in Cleveland, OH.

**About ARL-RAP**

The [Army Research Laboratory Research Associateship Program](#) (ARL-RAP) is designed to significantly increase the involvement of creative and highly trained scientists and engineers from academia and industry in scientific and technical areas of interest and relevance to the Army. Scientists and Engineers at the CCDC Army Research Laboratory (ARL)



**ORA Pathfinder**



Whether you are just starting your career or already at a senior level, ORAU offers internships, fellowships, research opportunities, and contract positions that can provide you with invaluable experience. Download the ORAU Pathfinder mobile app and find the right opportunity to propel you along your career path!

Visit ORAU Pathfinder [↗](#)



**Opportunity Title:** Robotic Locomotion and Whole Body Manipulation

**Opportunity Reference Code:** ARL-R-VTD-2047782940

help shape and execute the Army's program for meeting the challenge of developing technologies that will support Army forces in meeting future operational needs by pursuing scientific research and technological developments in diverse fields such as: applied mathematics, atmospheric characterization, simulation and human modeling, digital/optical signal processing, nanotechnology, material science and technology, multifunctional technology, combustion processes, propulsion and flight physics, communication and networking, and computational and information sciences.

**A complete application includes:**

- **Curriculum Vitae or Resume**
- **Three References Forms**
  - An email with a link to the reference form will be available in Zintellect to the applicant upon completion of the on-line application. Please send this email to persons you have selected to complete a reference.
  - References should be from persons familiar with your educational and professional qualifications (include your thesis or dissertation advisor, if applicable)
- **Transcripts**
  - Transcript verifying receipt of degree must be submitted with the application. Student/unofficial copy is acceptable




If selected by an advisor the participant will also be required to write a **research proposal** to submit to the ARL-RAP review panel for :

- Research topic should relate to a specific opportunity at ARL (see [Research Areas](#))
- The objective of the research topic should be clear and have a defined outcome
- Explain the direction you plan to pursue
- Include expected period for completing the study
- Include a brief background such as preparation and motivation for the research
- References of published efforts may be used to improve the proposal

A link to upload the proposal will be provided to the applicant once the advisor has made their selection.

**Questions about this opportunity?** Please email  
[ARLFellowship@orau.org](mailto:ARLFellowship@orau.org)

**Eligibility  
Requirements**

- **Degree:** Bachelor's Degree, Master's Degree, or Doctoral Degree received within the last 60 month(s).
- **Academic Level(s):** Faculty.
- **Discipline(s):**
  - **Chemistry and Materials Sciences** ([12](#) )
  - **Computer, Information, and Data Sciences** ([16](#) )
  - **Engineering** ([27](#) )

**Opportunity Title:** Robotic Locomotion and Whole Body Manipulation

**Opportunity Reference Code:** ARL-R-VTD-2047782940

- **Mathematics and Statistics** ([10](#) 👁)
- **Physics** ([16](#) 👁)
- **Science & Engineering-related** ([1](#) 👁)
- **Age:** Must be 18 years of age